

① omitted var. -

$$y = \beta_0 + \beta_1 x_1 + \dots + \beta_k x_k + \rho v + u$$

② $y = \beta^* + \beta_1^* x^* + u$

$x = x^* + e \Rightarrow x^* = x - e$

$y = \beta_0 + \beta_1 x + e$

$y = \beta_0^* + \beta_1^* (x - e) + u$
 $= \beta_0^* + \beta_1^* x + u - \beta_1^* e$

$\hat{\beta}_1 = \frac{\sum (x_i - \bar{x})(y_i - \bar{y})}{\sum (x_i - \bar{x})^2} \rightarrow \frac{Cov(x, y)}{V(x)} = \frac{Cov(x^* + e, \beta_0^* + \beta_1^* x^* + u)}{V(x^* + e)}$

$= \beta_1^* \left(\frac{V(x^*)}{V(x^*) + V(e)} \right)$

attenuation bias

③ $y_1 = \beta_0 + \beta_1 y_2 + \beta_2 x_2 + \dots + \beta_k x_k + u$
 $y_2 = \delta_0 + \delta_1 y_1 + \delta_2 m_2 + \dots + \delta_J m_J + e$

④ self-select (Gron)
 $w = 0/1$
 $y(0) = \beta_0 + \beta_1 x_1 + \dots + \beta_k x_k + u_1$
 $y(1) = \delta_0 + \delta_1 x_1 + \dots + \delta_k x_k + u_2$

$y(1) - y(0) = (\delta_0 - \beta_0) + (\delta_1 - \beta_1) x_1 + \dots +$

$w = \{y(1) \geq y(0)\} = \{\delta_0 - \beta_0 + u_2 - u_1 \geq 0\} \Rightarrow$ Roy model

$$y = w y(1) + (1-w) y(0)$$

$$= w (\beta_0 + \beta_1 x_1 + \dots + \beta_k x_k + u_2) + (1-w) (\beta_0 + \beta_1 x_1 + \dots + \beta_k x_k + u_1)$$

$$= \beta_0 + \beta_1 x_1 + \dots + \beta_k x_k + (\beta_0 - \beta_0 w) + (w u_2 + (1-w) u_1)$$

$$Y_i = A_i K_i^\alpha L_i^\beta$$

$$\ln Y_i = \ln A_i + \alpha \ln K_i + \beta \ln L_i$$

max $pf - vk - wL \Rightarrow k(A)$

quality = $\alpha + \beta$ quantity + ... + h

policy

Bank / shift-share

$$e_i = \sum_m \frac{e_{im} s_{im}}{e_m}$$

z_i

simulated ZV

结构: $y = \beta_0 + \beta_1 x + u \Leftarrow$ 因果

$\Rightarrow$ 1st stage: $x = \delta_0 + \delta_1 z + e \Leftarrow$ 相关性



$$\Rightarrow y = (\beta_0 + \beta_1 \delta_0) + \beta_1 \delta_1 z + u + \beta_1 e$$

简化式: $y = \eta_0 + \eta_1 z + \varepsilon$

ITT

$$\hat{\eta}_1 = \frac{\sum (z_i - \bar{z})(y_i - \bar{y})}{\sum (z_i - \bar{z})^2}$$

$$\hat{\delta}_1 = \frac{\sum (z_i - \bar{z})(x_i - \bar{x})}{\sum (z_i - \bar{z})^2}$$

$$\eta_1 = \beta_1 \delta_1$$

$$\beta_1 = \frac{\eta_1}{\delta_1}$$

Wald test $\hat{\beta}_1 = \frac{\hat{\eta}_1}{\hat{\delta}_1}$

$$\frac{\sum (z_i - \bar{z})(y_i - \bar{y})}{\sum (z_i - \bar{z})(x_i - \bar{x})}$$

$y_1 = \beta_0 + \beta_1 y_2 + \beta_2 z_1 + \dots + \beta_k z_{k-1} + u_1$

$E(y_1 | z_k) = \beta_0 + \beta_1 E(y_2 | z_k) + \beta_2 E(z_1 | z_k) + \dots$

$$y_1 = \beta_0 + \beta_1 y_2 + \beta_2 z_1 + \dots + \beta_k z_{k-1} + u_1$$

$z = \begin{pmatrix} z_1 \\ \vdots \\ z_k \end{pmatrix} \Rightarrow$ 所有外生变量

$E(y_1 | z) = \beta_0 + \beta_1 E(y_2 | z) + \beta_2 z_1 + \dots + \beta_k z_{k-1}$

$y_1 = \beta_0 + \beta_1 E(y_2 | z) + \beta_2 z_1 + \dots + \beta_k z_{k-1} + \varepsilon$

$\varepsilon = y_1 - E(y_1 | z)$

① $y_2 = \pi_0 + \pi_1 z_1 + \dots + \pi_k z_{k-1} + \pi_{k+1} z_k + e$

② $y_1 = \beta_0 + \beta_1 \hat{y}_2 + \beta_2 z_1 + \dots + \beta_k z_{k-1} + \varepsilon$

$$y_1 = \beta_0 + \beta_1 y_2 + \beta_2 y_3 + \beta_3 z_1 + \dots + \beta_k z_{k-2} + u_1$$

① $y_2 = \pi_0 + \pi_1 z_1 + \dots + \pi_{k-2} z_{k-2} + \pi_{k+1} z_{k+1} + \pi_{k+2} z_{k+2} + \dots + \pi_{k+1} z_{k+1} + v_2$

$\hat{y}_2$ $\hat{y}_3$ $\text{reg } \hat{z} \text{ on } [z_1, z_2, \dots, z_k, z_{k+1}, \dots] = F + v_5$

② $y_1 = \beta_0 + \beta_1 \hat{y}_2 + \beta_2 \hat{y}_3 + \beta_3 z_1 + \dots + \beta_k z_{k-2} + u$

$\hat{u} = y_1 - \hat{\beta}_0 - \hat{\beta}_1 \hat{y}_2 - \hat{\beta}_2 \hat{y}_3 - \hat{\beta}_3 z_1 - \dots$

$\hat{u} = y_1 - \hat{\beta} - \hat{\beta}_1 \hat{y}_2 - \hat{\beta}_2 \hat{y}_3$

$H_0: \pi_{k+1} = \pi_k = \pi_{k+1} = 0$

1st - F-value

$H_0: \sum_{k-1} = \sum_k = \sum_{k+1} = 0$

under identification test r/k

H_0 : 无内生性

H_1 : 有内生性

	OLS	IV
H_0	一致 有效	一致
H_1	不一致	一致

Hausman test

$y_1 = \beta_0 + \beta_1 y_2 + \dots + u_1 z_0$

$\begin{pmatrix} u_1 \\ u_2 \end{pmatrix} \sim N\left(0, \begin{pmatrix} 1 & \rho \\ \rho & 1 \end{pmatrix}\right)$

$$y_1 = \beta_0 + \beta_1 \underline{y_2} + \beta_2 z_1 + \dots + \beta_k z_{k-1} + u_1$$

$$1st \rightarrow y_2 = \pi_0 + \pi_1 z_1 + \dots + \pi_k z_k + v_2$$

$$(-) \quad u_1 = \rho v_2 + e$$

$$y_1 = \beta_0 + \beta_1 \underline{y_2} + \beta_2 z_1 + \dots + \beta_{k-1} z_{k-1} + \rho \underline{v_2} + e$$

$$\hat{v}_2$$

$$H_0: \rho = 0$$

$$(=) \quad \begin{pmatrix} u_1 \\ v_2 \end{pmatrix} \sim N \left(\begin{pmatrix} 0 \\ 0 \end{pmatrix}, \begin{pmatrix} 1 & \rho \\ \rho & 1 \end{pmatrix} \right)$$

$\Downarrow$
MLE

$$f(y_1, y_2 | \dots)$$

LIML